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# Raspberry Pi with MATLAB Using SPI and I2C

Hans-Petter Halvorsen

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- <u>Raspberry Pi</u>
- MATLAB
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- **SPI** Overview and Examples
  - <u>ADC MCP3002</u>
  - <u>TMP36</u> Analog Temperature Sensor + ADC MCP3002

These parts are covered in more detail in a previous Tutorial

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# Raspberry Pi

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## **Raspberry Pi**

**GPIO** Pins



Power Supply (USB C) microHDMI x 2

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# MATLAB

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### MATLAB

•••	MATLAB	R2020b - academic use
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<ul> <li>Name *</li> <li>slprj</li> <li>examples.m</li> <li>mass_spring_damper.mdl</li> <li>mass_spring_damper.slxc</li> <li>mass_spring_damper_script.m</li> </ul>	<pre>2 Editor = /Gets/halvorsen/Jobwholds/hallab/hals_sp [ mass_spring_damper_script.m × + 1 %Script of mass-spring-damper 2 %Hans-Petter Halvorsen. 20.11 3 4 %Modell Parameters 5 - x_init=4; %[m]. Initial posit 6 - dxdt_init=0; %[m/s]. Initial 7 - m=20; %[kg]</pre>	IntermediationValuesimulator.2009ion.Speed.Workspace $Value$ $Value$ $Value$ $F_1$ $A$ $F_0$ $O$ $K$ $Z$ $Mane A$ $Value$ $Val$
	8 - c=4; %[N/(m/s)] 9 - k=2; %[N/m] 10 - t_step_F=50; %[s] 11 - F_0=0; %[N] 12 - F_1=4; %[N] 13 14 %Simulator Settings 15 + store120; %[s]	<ul> <li>MATLAB is a tool for technical computing, computation and</li> </ul>
	15 -       t_stop=100; %[s]         16 -       T_s=t_stop/1000; %[s]         17 -       options=simset('solver', 'ode         18	<ul> <li>visualization in an integrated environment.</li> <li>MATLAB is an abbreviation for MATrix LABoratory</li> </ul>
mass_spring_damper_script.m (Script) Script of mass-spring-damper simulato	Command Window >> mass_spring_damper_script fy >>	<ul> <li>It is well suited for matrix manipulation and problem solving related to Linear Algebra, Modelling, Simulation and Control applications, etc.</li> <li>MATLAR is popular in Universities. Teaching and Research and</li> </ul>
		Development (R&D)
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# MATLAB Support Package for Raspberry Pi

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### Raspberry Pi + MATLAB

MATLAB Support Package for Raspberry Pi



With MATLAB Support Package for Raspberry Pi, the Raspberry Pi is connected to a computer running MATLAB. Processing is done on the computer with MATLAB.

https://mathworks.com/hardware-support/raspberry-pi-matlab.html

## Raspberry Pi + MATLAB



Raspberry Pi

#### MATLAB Support Package for Raspberry Pi



Getting Started with MATLAB Support Package for Raspberry Pi: <u>https://youtu.be/32ByiUdOwsw</u>

#### Hardware Setup



Getting Started with MATLAB Support Package for Raspberry Pi: <u>https://youtu.be/32ByiUdOwsw</u>

#### **Test Hardware**

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New Script Li	New New Open Compare In Compare I	Image: Save with the workspace       Image: Save with the workspace	<sup>™</sup> Community        Help <sup>™</sup> Learn MATLAB RESOURCES
← → B	🗄 🔀 💭 📙 🕨 C: 🕨 Users 🕨 hansha	Documents  MATLAB	<b>~</b>
Current F	Folder 🐨	ommand Window 📀	Workspace 💿
	lame ▲	>> r = raspi r =	Name ▲ Value r 1x1 raspi
r = raspi()		<u>raspi</u> with properties: DeviceAddress: '172.20.10.11' Port: 18734 BoardName: 'Raspberry Pi 4 Model B' AvailableLEDs: ('led0')	
or		<pre>AvailableDigitalPins: [4,5,6,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,27] AvailableSPIChannels: {'CE0','CE1'} AvailableI2CBuses: {'i2c-1'} AvailableWebcams: {} I2CBusSpeed: 100000</pre>	
r = raspi(i	paddres)	Supported peripherals	
	Select a file to view details		

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# Raspberry Pi GPIO

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### **GPIO**





## **GPIO Features**

The GPIO pins are Digital Pins which are either True (+3.3V) or False (0V). These can be used to turn on/off LEDs, etc.

The Digital Pins can be either Output or Input. In addition, some of the pins also offer some other Features:

- PWM (Pulse Width Modulation)
   Digital Buses (for reading data from Sensors, etc.):
- I2C
- SPI



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### **I2C**

Multiple devices can be connected to the I2C pins on the Raspberry Pi Master – Device that generates the clock and initiates communication with slaves Slave – Device that receives the clock and responds when addressed by the master.

Raspberry Pi



ADC, DAC, Sensor, etc. with I2C Interface

. . .

## Access I2C on Raspberry Pi

enableI2C(mypi) enables the I2C bus at its default bus speed of 100000 bps.

You can then use the Raspberry Pi hardware board pins I2C1\_SDA (GPIO 2) and I2C1\_SCL (GPIO 3) as I2C pins and interface the Raspberry Pi board with any I2C device to exchange data.

The I2C bus is enabled by default. To disable I2C, use disableI2C.

## **I2C Wiring on Raspberry Pi**

#### **GPIO 40 pins Connector**





Note! The I2C pins include a fixed 1.8 k $\Omega$  pull-up resistor to 3.3v.

### MATLAB - I2C Interface

#### **I2C Interface**

Use the Raspberry Pi™'s I2C interface

#### Objects

raspi	Connection to Raspberry Pi board
i2cdev	Connection to device on Raspberry Pi hardware

#### Functions

scanI2CBus	Scan I2C bus device addresses
read	Read data from I2C device
write	Write data to I2C device
readRegister	Read from register on I2C device
writeRegister	Write to register on I2C device
enableI2C	Enable I2C interface
disableI2C	Disable I2C interface

https://se.mathworks.com/help/suppor tpkg/raspberrypiio/i2cinterface.html?s\_tid=CRUX\_lftnav

## **Get Raspberry Pi Information**

clear rpi;
rpi = raspi();

**<u>raspi</u>** with properties:

Command Window

DeviceAddress: '192.168.137.125' Port: 18734 BoardName: 'Raspberry Pi 2 Model B' AvailableLEDs: {'led0'} AvailableDigitalPins: [4,5,6,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,27] AvailableSPIChannels: {'CE0','CE1'} AvailableI2CBuses: {'i2c-1'} AvailableWebcams: {} I2CBusSpeed: 100000

Supported peripherals

## **Get Raspberry Pi Information**



### Get I2C Address

Get the addresses of I2C devices that are attached to the I2C bus

```
clear rpi;
rpi = raspi();
scanI2CBus(rpi,'i2c-1')
```

```
Command Window
  >> i2c get devices
  ans =
     1×1 cell array
       {'0x48'}
```

### **Basic Read Example**

```
clear rpi;
rpi = raspi();
i2caddress = '0x48';
device = i2cdev(rpi,'i2c-1', i2caddress);
value = read(device,1);
disp(value);
```

### **Basic Write Example**

```
clear rpi;
rpi = raspi();
i2caddress = '0x62';
device = i2cdev(rpi,'i2c-1', i2caddress);
value = 4092;
write(device, value);
```

## **Read Register**

```
clear rpi;
rpi = raspi();
i2caddress = '0x48';
device = i2cdev(rpi,'i2c-1', i2caddress);
data = readRegister(device, 14);
disp(data);
```

Read the value of register 14 from the I2C device

### Write Register

```
clear rpi;
rpi = raspi();
i2caddress = '0x62';
device = i2cdev(rpi,'i2c-1', i2caddress);
data = hex2dec('08');
type = 'uint8'
writeRegister(device,3,data,type)
```

Write a scalar hexadecimal value, hex2dec('08'), to register 3 on the I2C device

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# TC74

#### **Temperature Sensor with I2C Interface**

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## **TC74** Temperature Sensor

#### **I2C** Interface

TC74A0-5.0VAT





- The TC74 acquires and converts temperature information from its onboard solid-state sensor with a resolution of ±1°C.
- It stores the data in an internal register which is then read through the serial port.
- The system interface is a slave SMBus/I2C port, through which temperature data can be read at any time.

Datasheet: https://ww1.microchip.com/downloads/en/DeviceDoc/21462D.pdf

## TC74 Wiring



Raspberry Pi GPIO Pins

### Wiring



## **Read Temperature Example**

You read the temperature value directly as a number in degrees Celsius. No conversion or anything is necessary



#### **Reading Temperature and Plotting**



```
clear;
rpi = raspi();
disp('Initialization...')
i2caddress = '0x48';
device = i2cdev(rpi,'i2c-1', i2caddress);
N = 10;
T = 2;
x = 1:N;
y = zeros(N, 1);
disp('Start Reading Temperature Data...')
for i = 1:N
    temperature = read(device,1);
    disp("T=" + temperature + "°C");
    y(i) = temperature;
    pause(T);
end
plot(x, y, '-o')
title('Temperature TC74')
xlabel('Time')
ylabel('T[°C]')
xmin=1;xmax=N;ymin=20;ymax=30;
axis([xmin xmax ymin ymax])
clear device;
```

clear rpi;

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# SPI

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## SPI

- Serial Peripheral Interface (SPI)
- SPI is an interface to communicate with different types of electronic components like Sensors, Analog to Digital Converts (ADC), etc. that supports the SPI interface
- Thousands of different Components and Sensors supports the SPI interface

### **SPI Interface**

SPI devices communicate in full duplex mode using a master-slave architecture with a single master



The SPI bus specifies four logic signals:

- **SCLK**: Serial Clock (output from master)
- MOSI: Master Out Slave In (data output from master)
- MISO: Master In Slave Out (data output from slave)
- CE (often also called SS Slave Select): Chip Select (often active low, output from master)

## SPI Wiring on Raspberry Pi

#### GPIO 40 pins Connector





### **MATLAB - SPI Interface**

#### SPI Interface

https://se.mathworks.com/help/supportpkg/raspb errypiio/spi-interface.html?s\_tid=CRUX\_lftnav

Use the Raspberry Pi<sup>™</sup>'s SPI interface

#### Objects

raspi	Connection to Raspberry Pi board
spidev	Connection to SPI device on Raspberry Pi hardware

#### Functions

writeRead	Write data to and read data from SPI device	
enableSPI	Enable SPI interface	
disableSPI	Disable SPI interface	

### **Find SPI Channels**

clear rpi
rpi = raspi();
rpi.AvailableSPIChannels

Com	Command Window			
	>> rp_ex			
	ans =			
	1×2 <u>cell</u> arra	у		
	{'CE0'}	{'CE1'}		

### SPI Example

clear rpi; rpi = raspi();				
<pre>spidevice = spidev(mypi,'CE1',0)</pre>				
<pre>wrdata = [hex2dec('08') hex2dec('D4')]; %Just an example</pre>				
<pre>dataout = writeRead(spidevice, wrdata)</pre>				
Write D	ata Read D	Data		

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# ADC with SPI interface

Analog to Digital Converter

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### ADC

- The Raspberry Pi has only Digital pins on the GPIO connector
- If you want to use an Analog electric component or an Analog Sensor together with Raspberry Pi, you need to connect it through an external ADC chip
- ADC Analog to Digital Converter

#### ADC



# MCPxxx ADC chip

The MCPxxx family of ADC chips uses a SPI Interface

10-bit analog to digital converters (ADC):

- MCP3008/3208/3304 have 8 channels (0-7)
- MCP3004/3204/3302 have 4 channels (0-3)
- MCP3002/3202 have 2 channels (0-1)
- MCP3001/3201/3301 only have 1 channel.

MCP3002 will be used in this Tutorial, but all should work in the same manner

#### Analog Input Using SPI (MCP3008):

https://se.mathworks.com/help/supportpkg/raspberrypiio/ref/analog-input-using-spi.html

#### Sensors:

https://se.mathworks.com/help/supportpkg/raspberrypiio/sensors.html?s\_tid=CRUX\_lftnav

## MCP3002 ADC chip

The MCP3002 is a 10-bit analog to digital converter with 2 channels (0-1).

The MCP3002 uses a SPI Interface



http://ww1.microchip.com/downloads/en/DeviceDoc/21294E.pdf

<u>https://learn.sparkfun.com/tutorials/python-programming-tutorial-getting-started-with-the-raspberry-pi/experiment-3-spi-and-analog-input</u>

## Wiring



https://sites.google.com/a/joekamphaus.net/raspberry-pi-spi-interface-to-mcp3002/



#### **Read Data from ADC**

For test purpose we start by wiring a 1.5V Battery to the CH0 (+) and CH1(-) pins on the ADC



Wire the other pins to the Raspberry Pi according to previous wiring schema

#### **Channel Configuration**



#### Potentiometer



### Wiring



#### **Read Data from ADC**

```
clear;
rpi = raspi();
spidevice = spidev(rpi, 'CEO', 0);
data = uint16(writeRead(spidevice, [1, bin2dec('00000000'), 0]));
highbits = bitand(data(2), bin2dec('11'));
adcvalue = double(bitor(bitshift(highbits, 8), data(3)));
voltage = (3.3/1024) * adcvalue;
```

disp(voltage);

clear spidevice; Clear rpi; You should improve the Code by making a MATLAB Function, then use the function inside a Loop for continuous readings

https://se.mathworks.com/help/supportpkg/raspberrypiio/ref/analog-input-using-spi.html

#### Measure Voltage at CH0

- MCP300x uses the SPI interface to communicate with the SPI controller which in this case is Raspberry Pi hardware.
- An SPI transaction between MCP300x and Raspberry Pi consist of 3 bytes.
- Raspberry Pi hardware sends a byte containing a value of '1' to MCP300x.
- At the same time, MCP300x sends a "do not care" byte to Raspberry Pi hardware.
- Raspberry Pi hardware sends another byte to the MCP300x with the most significant 4 bits containing a value of '**1000**'. This byte indicates to the MCP300x that a single-ended voltage measurement at CH0 is requested.
- At the same time, MCP300x sends the **bits 9 and 10** of the ADC measurement.
- Finally, Raspberry Pi hardware sends a "do not care" byte and at the same time reads the **least significant 8 bits** of the voltage measurement.
- The 10-bit value read from MCP300x is then converted to a voltage value.

```
clear;
rpi = raspi();
spidevice = spidev(rpi, 'CE0', 0);
N = 20;
for i = 1:N
    data = uint16(writeRead(spidevice, [1, bin2dec('00000000'), 0]));
    highbits = bitand(data(2), bin2dec('11'));
    adcvalue = double(bitor(bitshift(highbits, 8), data(3)));
    %disp(adcvalue);
    voltage = (3.3/1024) * adcvalue;
    value = sprintf('%.2f', voltage);
                                               But turning on the
    disp(value);
                                           Potentiometer, you should
    pause(1);
end
                                           see the voltage goes from
                                                0V to 3.3V (max)
clear mcp3002;
```

clear rpi;

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# **TMP36**

#### **Analog Temperature Sensor**

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#### **TMP36** Temperature Sensor



A Temperature sensor like TM36 use a solid-state technique to determine the temperature.

They use the fact as temperature increases, the voltage across a diode increases at a known rate.

https://learn.adafruit.com/tmp36-temperature-sensor

#### **TMP36** Temperature Sensor



This gives:

$$y - 25 = \frac{50 - 25}{1 - 0.75}(x - 0.75)$$

Then we get the following formula: y = 100x - 50

Convert form Voltage (V) to degrees Celsius

From the Datasheet we have:

 $\begin{array}{l} (x_1,y_1) \ = \ (0.75V,25^\circ C) \\ (x_2,y_2) \ = \ (1V,50^\circ C) \end{array}$ 

There is a linear relationship between Voltage and degrees Celsius:

$$y = ax + b$$

We can find a and b using the following known formula:

$$y - y_1 = \frac{y_2 - y_1}{x_2 - x_1} (x - x_1)$$

#### Measure Temperature with an ADC



Wire a TMP36 temperature sensor to the first channel of an MCP3002 analog to digital converter and the other pins to +3.3V and GND



#### Wiring



```
clear;
rpi = raspi();
spidevice = spidev(rpi, 'CE0', 0);
N = 20;
for i = 1:N
    data = uint16(writeRead(spidevice, [1, bin2dec('10000000'), 0]));
    highbits = bitand(data(2), bin2dec('11'));
    adcvalue = double(bitor(bitshift(highbits, 8), data(3)));
    %disp(adcvalue);
    voltage = (3.3/1024) * adcvalue;
    tempC = 100 * voltage - 50;
    value = sprintf('%.2f', tempC);
    disp(value);
    pause (5);
end
clear spidevice;
```

```
clear rpi;
```

# Summary

- Raspberry Pi + MATLAB
- MATLAB Support Package for Raspberry Pi
- I2C Overview and Examples
  - -TC74 I2C Temperature Sensor
- SPI Overview and Examples
  - ADC MCP3002 + TMP36 Analog Temperature Sensor

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